



KAMIDRIVE
中空旋转平台领航者

产品综合目录

PRODUCT CATALOG

KAMIDRIVE

Hollow Rotary Platform Reducer

☎ 0769-81881093

🌐 <http://www.kamidrive.com/>

📍 广东省东莞市大岭山镇杨朗路君山科技园



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VINAPOWER AUTOMATION CO., LTD

公司简介 Company profile

Guangdong Kami Transmission Technology Co., Ltd. specializes in the production of high-precision hollow rotary platforms and planetary reducers. It is a Chinese-Japanese joint venture invested by Fuji FA System Control Co., Ltd. of Japan. We integrate R&D, design, production, sales and service. We introduce mature and stable processing, production concepts of Japanese companies. The products are widely used in CNC machine tools, cutting machines, welding machines, packaging and printing machines, textile machines, woodworking machines, industrial robots, semiconductor machinery, lithium batteries, 3C production lines, etc. At present, the company has registered many of trademarks, utility patents and invention patents in China, Southeast Asia, the Middle East, Europe and other places. We will continue to invest more in R&D and product innovation, emphasizing product perfection to contribute to the intelligent development of technology in the world.

The company's headquarters is located in Dongguan, Guangdong - a famous manufacturing city in China. We utilize the supporting economic and geographical transportation advantages to radiate the national and overseas markets. Besides, in order to better serve the pre-sales and after-sales requirements of agents and customers, we have established offices in the following regions: Beijing Office, Xi'an Office, Shanghai Office, Wuxi Office, Quanzhou Office, Guangzhou Office, Shenzhen Office, Chongqing Office, and Hong Kong Office

- ➡ Company philosophy: Sincere, courageous, and responsibility.
- ➡ Company product policy: Excellence and continuous innovation
- ➡ Company product positioning: High quality, high precision and high efficiency

目录 CATALOGUE

Product samples, combination samples ----- 03

KTN series hollow rotating platform (with servo or step motor)

KTN60-5K-SV -----	04
KTN85-5K-SV -----	05
KTN85-10K-SV -----	06
KTN130-10K-SV -----	07
KTN130-18K-SV -----	08
KTN170-10K-SV -----	09
KTN200-10K-SV -----	10
KTN200-18K-SV -----	11
KTN280-10K-SV -----	12
KTN450-10K-SV -----	13
KTN700-20K-SV -----	14

KTX series hollow rotating platform (with planetary reducer)

KTX85 -----	15
KTX130 -----	16
KTX200 -----	17
KTX280 -----	18
KTX700 -----	19

KTC series hollow rotating platform (with servo or planetary reducer)

KTC40 -----	20
KTC60 -----	21
KTC90 -----	22
KTC120 -----	23

KTY series hollow rotating platform (with steering gear)

KTY85 -----	24
KTY130 -----	25
KTY200 -----	26

Non-standard customized models

Four or five axis 60-5K/85-10K -----	27
Four or five axis 85-5K/85-10K -----	28
Four or five axis 85-10K/130-18K -----	29

KB series planetary reducer

KB060/KBR060 -----	30
KB090/KBR090 -----	31
KB115/KBR115 -----	32
KBY060 -----	33
KBY090 -----	34

System configuration description

Hollow Rotating Platform Application Description -----	35
Hollow Rotating Platform System Composition -----	36
Hollow Rotating Platform Parameters and Terms -----	37
Positioning accuracy detection and selection -----	38

KTN60-5K-SV

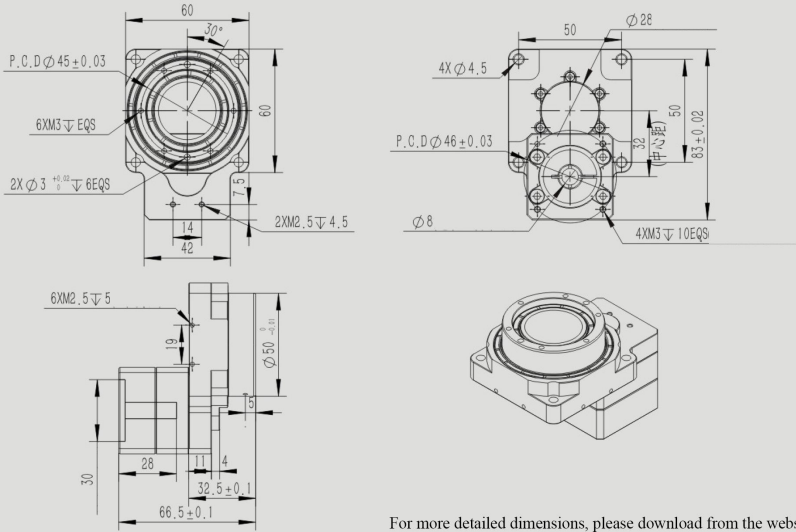


How to order :

Series	Dimension	Reduction ratio	Motor type
KTN	60	05K	Various brands servo motor 50 -100W/Step motor size 42

Specification

Motor specification	Various brands servo motor 50 -100W/Step motor size 42
Bearing structure	Crossed Roller Bearing
Allowable torque	5.2N.m
Allowable speed	250rpm
Reduction ratio	1:5
Allowable axial load	250N
Posiitoning accuracy	±15arcsec
Repeat positioning accuracy	±5arcsec
Rotating platform parallelism	±0.003mm
Rotating platform concentricity	±0.003mm
Protection level	IP63
Accuracy life	20000H
Mass	0.8KG



For more detailed dimensions, please download from the website

KTN85-5K-SV

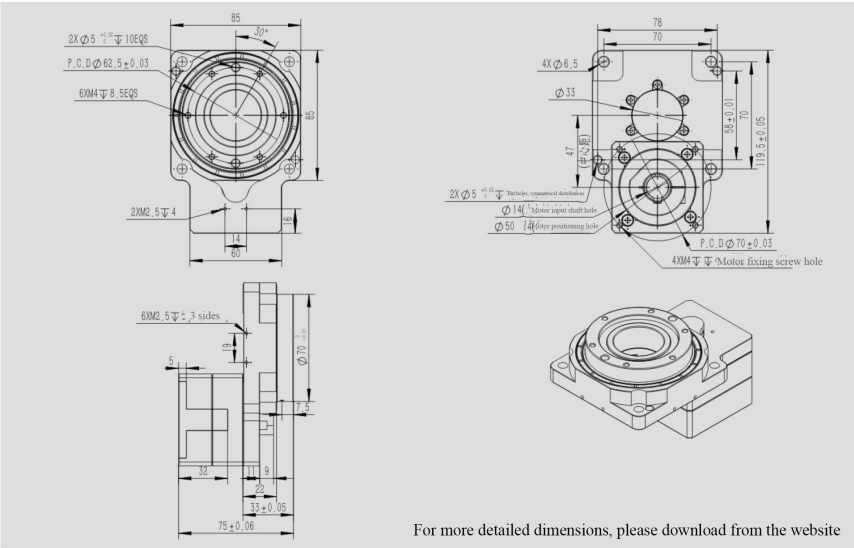


How to order :

Series	Dimension	Reduction ratio	Motor type
KTN	85	05K	Various brands servo motor 200-400W/Step motor size 57

Specification

Motor specification	Various brands servo motor 200 -400W/Step motor size 57
Bearing structure	Crossed Roller Bearing
Allowable torque	8N.m
Allowable speed	250rpm
Reduction ratio	1:5
Allowable axial load	500N
Posiitoning accuracy	±15arcsec
Repeat positioning accuracy	±5arcsec
Rotating platform parallelism	±0.003mm
Rotating platform concentricity	±0.003mm
Protection level	IP63
Accuracy life	20000H
Mass	1.3KG



For more detailed dimensions, please download from the website

KTN85-10K-SV

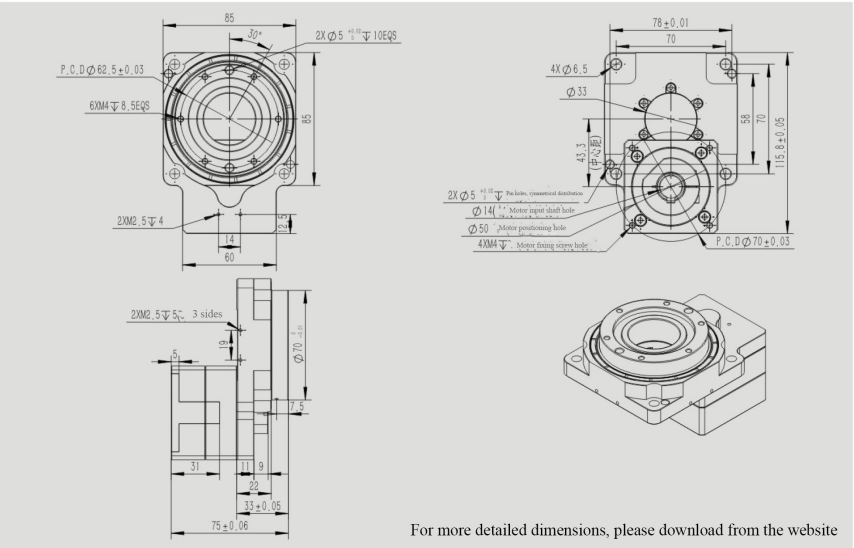


How to order :

Series	Dimension	Reduction ratio	Motor type
KTN	85	10K	Various brands servo motor 200-400W/Step motor size 57

Specification

Motor specification	Various brands servo motor 200 -400W/Step motor size 57
Bearing structure	Crossed Roller Bearing
Allowable torque	8N.m
Allowable speed	250rpm
Reduction ratio	1:10
Allowable axial load	500N
Posiitoning accuracy	±15arcsec
Repeat positioning accuracy	±5arcsec
Rotating platform parallelism	±0.003mm
Rotating platform concentricity	±0.003mm
Protection level	IP63
Accuracy life	20000H
Mass	1.3KG



For more detailed dimensions, please download from the website

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Series	Dimension	Reduction ratio	Motor type
KTN	130	10K	Various brands servo motor 200-400W/Step motor size 57

Series	Dimension	Reduction ratio	Motor type
KTN	130	10K	Various brands servo motor 200-400W/Step motor size 57

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Series	Dimension	Reduction ratio	Motor type
KTN	130	18K	Various brands servo motor 200-400W/Step motor size 57

Series	Dimension	Reduction ratio	Motor type
KTN	130	18K	Various brands servo motor 200-400W/Step motor size 57

Technical drawing of a motor bracket showing three views: front, side, and isometric.

Front View Dimensions:

- Overall width: 120
- Inner width: 110
- Outer diameter: $\varnothing 110$
- Height: 90
- Bottom flange width: 60
- Flange thickness: 14
- Mounting holes: 2X $\varnothing 5$
- Motor input holes: 2X $\varnothing 5$ (Even distribution)
- Motor input holes: 6X $\varnothing 5$ (Even distribution)
- Motor input hole pitch circle diameter: P.C.D. $\varnothing 104 \pm 0.05$
- Motor input hole size: 2X M2.5

Side View Dimensions:

- Overall height: 114
- Top flange thickness: 5
- Top flange width: 19
- Top flange hole size: 6X M2.5 (3 sides)
- Top flange hole pitch circle diameter: $\varnothing 114$
- Top flange hole size: 5
- Top flange hole pitch circle diameter: $\varnothing 114$
- Top flange hole size: 13
- Top flange hole pitch circle diameter: $\varnothing 114$
- Top flange hole size: 14
- Top flange hole pitch circle diameter: $\varnothing 114$
- Top flange hole size: 7
- Top flange hole pitch circle diameter: $\varnothing 114$
- Top flange hole size: 40
- Top flange hole pitch circle diameter: $\varnothing 114$
- Top flange hole size: 62

Isometric View Dimensions:

- Overall width: 130
- Overall height: 130
- Overall depth: 158.8 ± 0.05
- Mounting holes: 4X $\varnothing 9$
- Motor input hole pitch circle diameter: P.C.D. $\varnothing 70 \pm 0.05$
- Motor input hole size: 4X M4
- Motor input hole pitch circle diameter: $\varnothing 14$
- Motor input hole size: $\varnothing 50$

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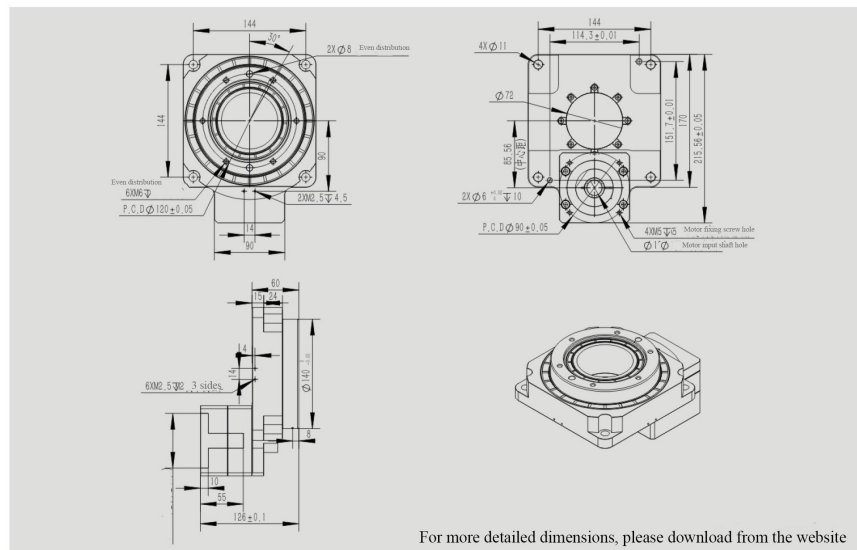
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Series	Dimension	Reduction ratio	Motor type
KTN	170	10K	Various brands servo motor 750W

Series	Dimension	Reduction ratio	Motor type
KTN	170	10K	Various brands servo motor 750W

Specification	
Motor specification	Various brands servo motor 750W
Bearing structure	Crossed Roller Bearing
Allowable torque	48N.m
Allowable speed	200rpm
Reduction ratio	1:10
Allowable axial load	3000N
Posiitoning accuracy	±30arcsec
Repeat positioning accuracy	±5arcsec
Rotating platform parallelism	±0.003mm
Rotating platform concentricity	±0.005mm
Protection level	IP63
Accuracy life	20000H
Mass	7KG

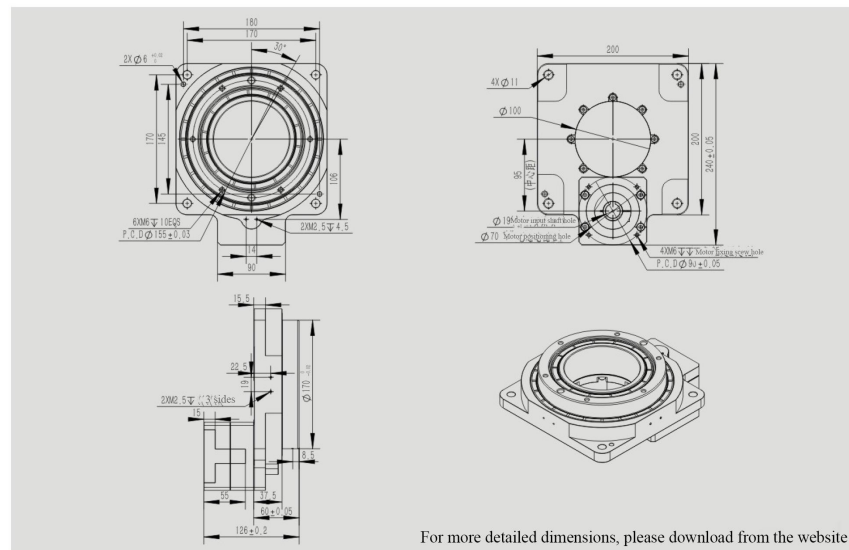


For more detailed dimensions, please download from the website

Series	Dimension	Reduction ratio	Motor type
KTN	200	10K	Various brands servo motor 750W

Series	Dimension	Reduction ratio	Motor type
KTN	200	10K	Various brands servo motor 750W

Specification	
Motor specification	Various brands servo motor 750W
Bearing structure	Crossed Roller Bearing
Allowable torque	65N.m
Allowable speed	200rpm
Reduction ratio	1:10
Allowable axial load	4000N
Posiitoning accuracy	±30arcsec
Repeat positioning accuracy	±5arcsec
Rotating platform parallelism	±0.003mm
Rotating platform concentricity	±0.005mm
Protection level	IP63
Accuracy life	20000H
Mass	7.8KG



For more detailed dimensions, please download from the website

KTN200-18K-SV



How to order :			
Series	Dimension	Reduction ratio	Motor type
KTN	200	18K	Various brands servo motor 750W

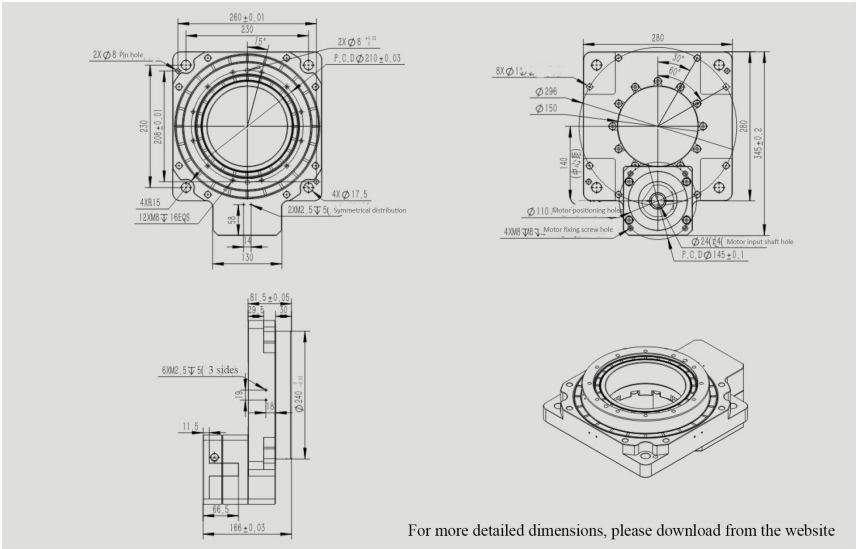
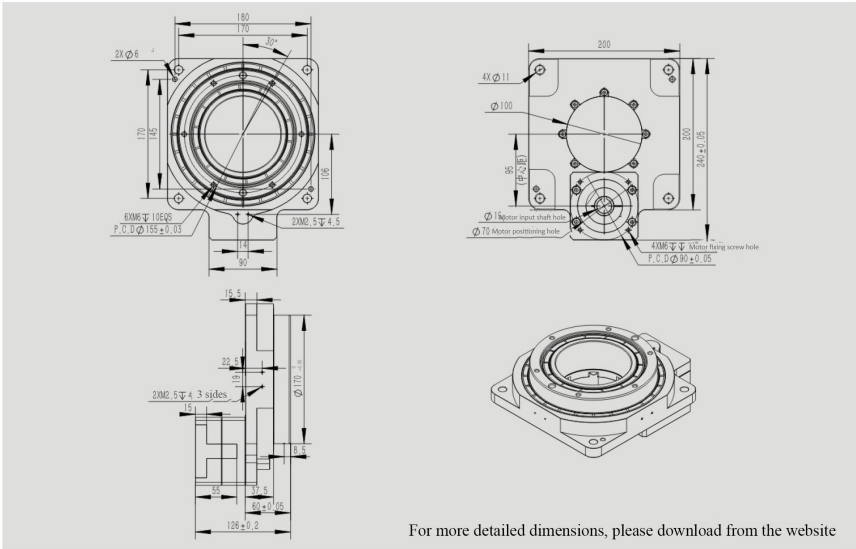
Specification	
Motor specification	Various brands servo motor 750W
Bearing structure	Crossed Roller Bearing
Allowable torque	65N.m
Allowable speed	200rpm
Reduction ratio	1:18
Allowable axial load	4000N
Posiitoning accuracy	±30arcsec
Repeat positioning accuracy	±5arcsec
Rotating platform parallelism	±0.003mm
Rotating platform concentricity	±0.005mm
Protection level	IP63
Accuracy life	20000H
Mass	7.8KG

KTN280-10K-SV



How to order :			
Series	Dimension	Reduction ratio	Motor type
KTN	280	10K	Various brands servo motor 1000-2500W

Specification	
Motor specification	Various brands servo motor 1000-2500W
Bearing structure	Crossed Roller Bearing
Allowable torque	86.7N.m
Allowable speed	150rpm
Reduction ratio	1 : 10
Allowable axial load	4840N
Posiitoning accuracy	±60arcsec
Repeat positioning accuracy	±10arcsec
Rotating platform parallelism	0.005mm
Rotating platform concentricity	0.007mm
Protection level	IP63
Accuracy life	20000H
Mass	25KG

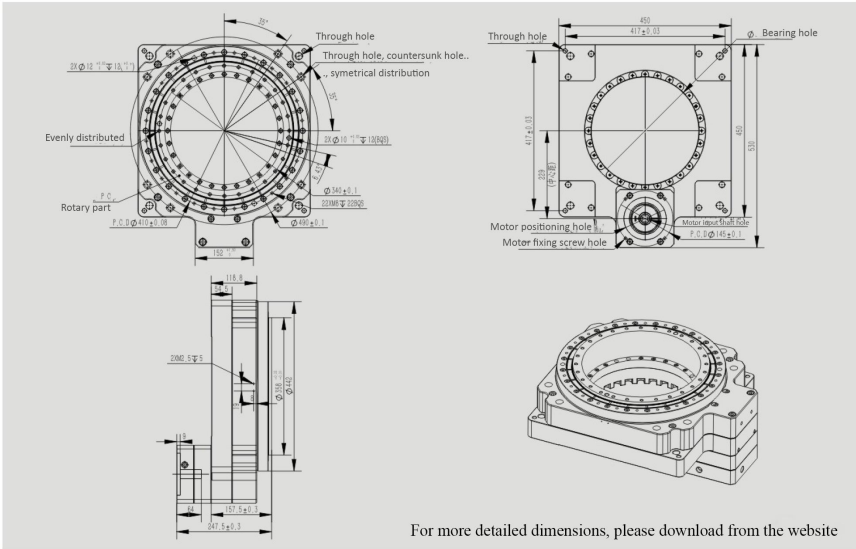


KTN450-10K-SV

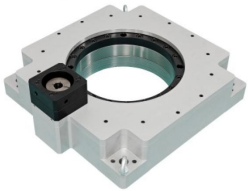


How to order :			
Series	Dimension	Reduction ratio	Motor type
KTN	450	10K	Various brands servo motor 1000-2500W

Specification	
Motor specification	Various brands servo motor 1000-2500W
Bearing structure	Crossed Roller Bearing
Allowable torque	156N.m
Allowable speed	100rpm
Reduction ratio	1:10
Allowable axial load	10000N
Posiitoning accuracy	±80arcsec
Repeat positioning accuracy	±15arcsec
Rotating platform parallelism	±0.007mm
Rotating platform concentricity	±0.015mm
Protection level	IP63
Accuracy life	20000H
Mass	80KG

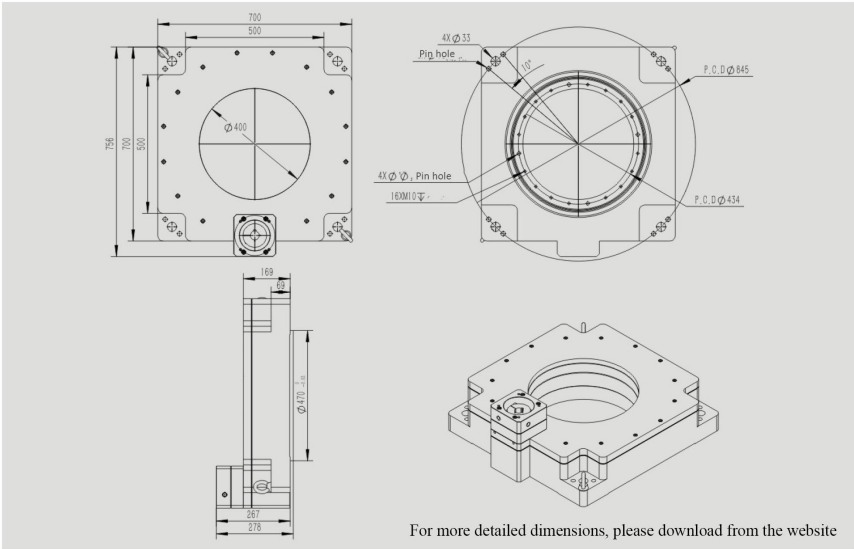


KTN700-20K-SV



How to order :			
Series	Dimension	Reduction ratio	Motor type
KTN	700	20K	Various brands servo motor 1000-2500W

Specification	
Motor specification	Various brands servo motor 1000-2500W
Bearing structure	Crossed Roller Bearing
Allowable torque	197N.m
Allowable speed	100rpm
Reduction ratio	1:20
Allowable axial load	13000N
Posiitoning accuracy	±95arcsec
Repeat positioning accuracy	±20arcsec
Rotating platform parallelism	±0.009mm
Rotating platform concentricity	±0.020mm
Protection level	IP63
Accuracy life	20000H
Mass	285KG



KTX series hollow rotating platform—equipped with planetary reducer + servo motor

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KTX series hollow rotating platform—equipped with planetary reducer + servo motor

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KTX85



How to order :

Series	Dimension	Reduction ratio	Motor type
KTX	85	1:30/40/50/70/100	Various brands servo motor 200-400W/Step motor size 57

Specification

Motor specification	Various brands servo motor 200-400W/Step motor size 57
Bearing structure	Crossed Roller Bearing
Allowable torque	8N.m
Allowable speed	150rpm
Reduction ratio	1:30/40/50/70/100
Allowable axial load	500N
Positioning accuracy	±30arcsec
Repeat positioning accuracy	±15arcsec
Rotating platform parallelism	±0.003mm
Rotating platform concentricity	±0.003mm
Protection level	IP63
Accuracy life	20000H
Mass	2.5KG

KTX130

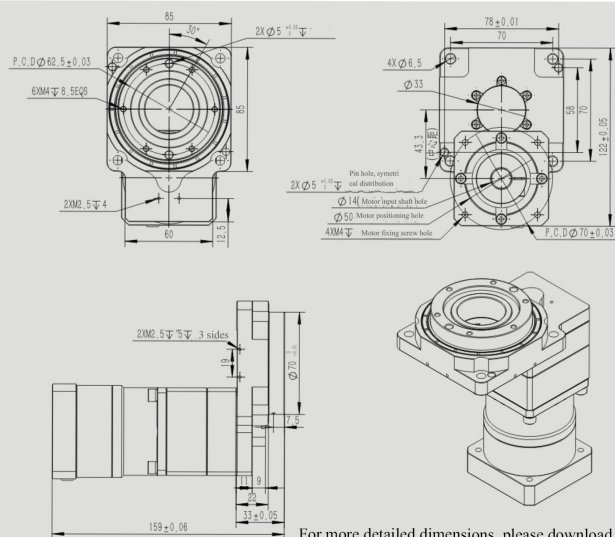


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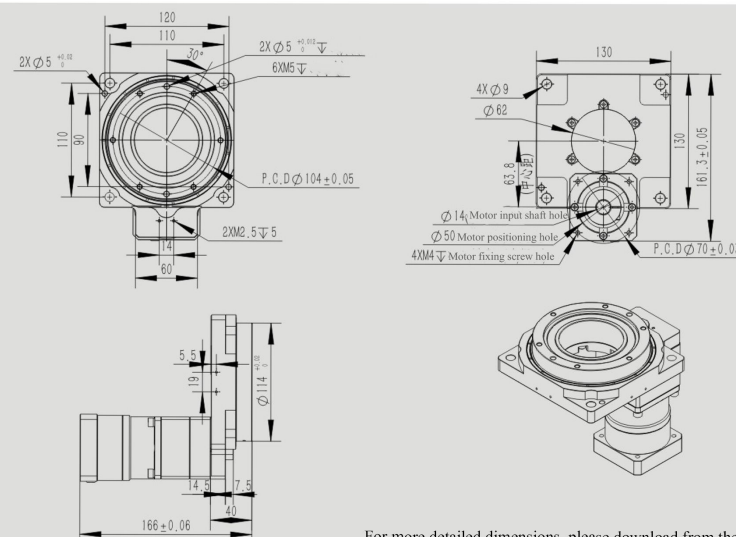
Series	Dimension	Reduction ratio	Motor type
KTX	130	1:30/40/50/70/100	Various brands servo motor 200-400W/Step motor size 57

Specification

Motor specification	Various brands servo motor 200-400W/Step motor size 57
Bearing structure	Crossed Roller Bearing
Allowable torque	32N.m
Allowable speed	150rpm
Reduction ratio	1:30/40/50/70/100
Allowable axial load	2000N
Positioning accuracy	±30arcsec
Repeat positioning accuracy	±15arcsec
Rotating platform parallelism	±0.005mm
Rotating platform concentricity	±0.005mm
Protection level	IP63
Accuracy life	20000H
Mass	4KG



For more detailed dimensions, please download from the website



For more detailed dimensions, please download from the website

KTX200

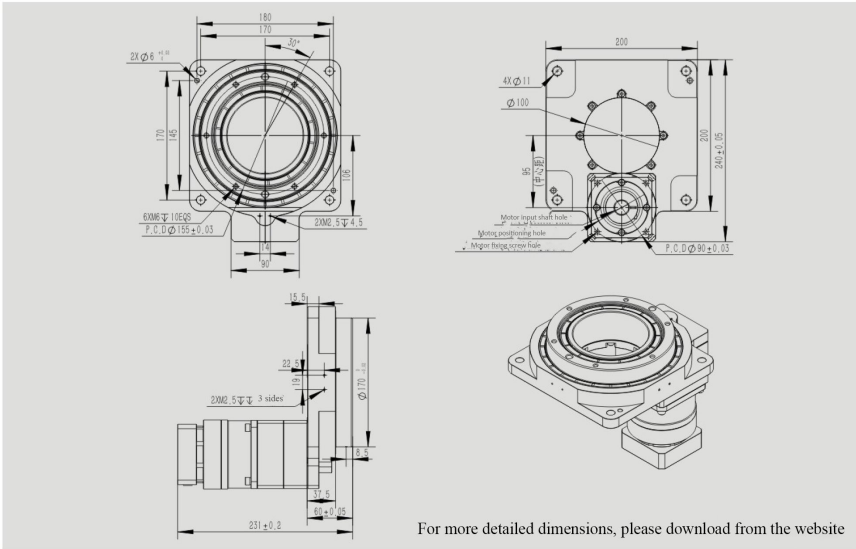


How to order :

Series	Dimension	Reduction ratio	Motor type
KTX	200	1:30/40/50/70/100	Various brands servo motor 750W

Specification

Motor specification	Various brands servo motor 750W
Bearing structure	Crossed Roller Bearing
Allowable torque	65N.m
Allowable speed	150rpm
Reduction ratio	1:30/40/50/70/100
Allowable axial load	4000N
Posiitoning accuracy	±40arcsec
Repeat positioning accuracy	±20arcsec
Rotating platform parallelism	±0.003mm
Rotating platform concentricity	±0.005mm
Protection level	IP63
Accuracy life	20000H
Mass	12KG



KTX280

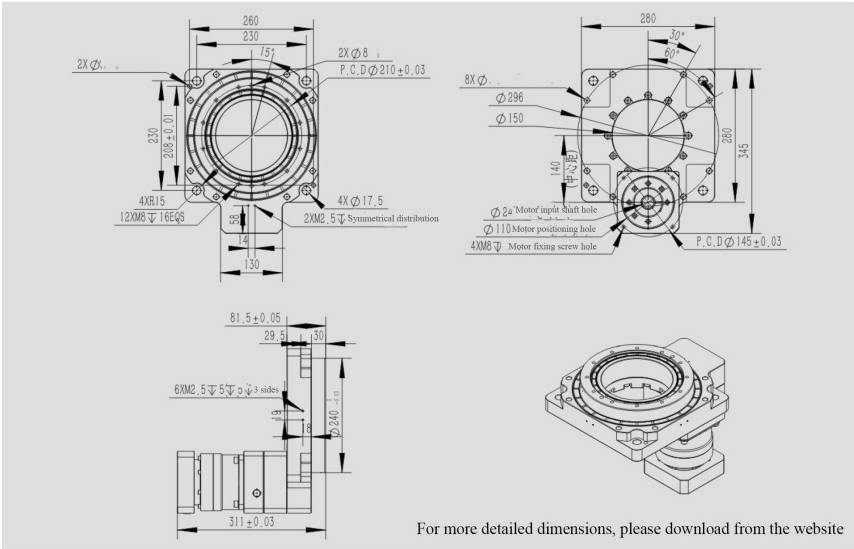


How to order :

Series	Dimension	Reduction ratio	Motor type
KTX	280	1:30/40/50/70/100	Various brands servo motor 1000-2500W

Specification

Motor specification	Various brands servo motor 1000-2500W
Bearing structure	Crossed Roller Bearing
Allowable torque	86.7N.m
Allowable speed	150rpm
Reduction ratio	1:30/40/50/70/100
Allowable axial load	4840N
Posiitoning accuracy	±70arcsec
Repeat positioning accuracy	±20arcsec
Rotating platform parallelism	±0.005mm
Rotating platform concentricity	±0.007mm
Protection level	IP63
Accuracy life	20000H
Mass	28KG



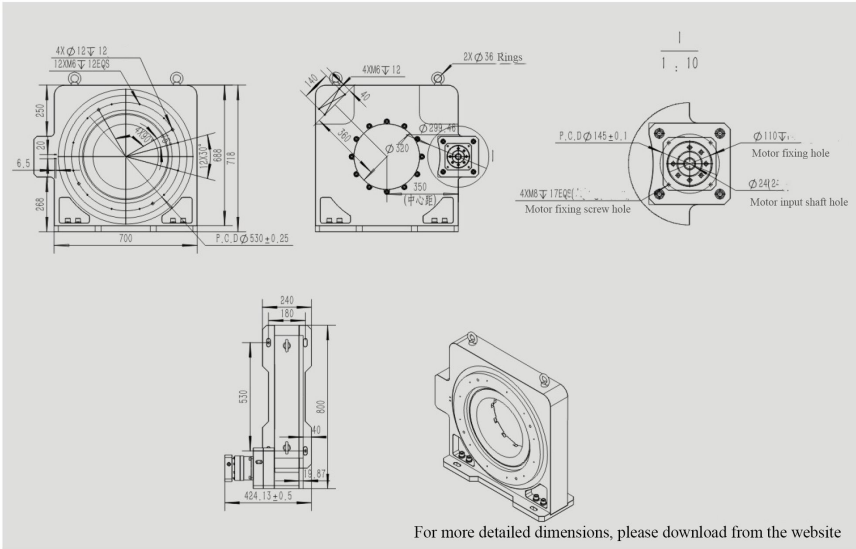
KTX700



How to order :

Series	Dimension	Reduction ratio	Motor type
KTN	700	1:30/40/50/70/100	Various brands servo motor 1000-2500W

Specification	
Motor specification	Various brands servo motor 1000-2500W
Bearing structure	Crossed Roller Bearing
Allowable torque	183N.m
Allowable speed	100rpm
Reduction ratio	1:30/40/50/70/100
Allowable axial load	12000N
Posiitoning accuracy	±95arcsec
Repeat positioning accuracy	±20arcsec
Rotating platform parallelism	±0.009mm
Rotating platform concentricity	±0.020mm
Protection level	IP63
Accuracy life	20000H
Mass	275KG



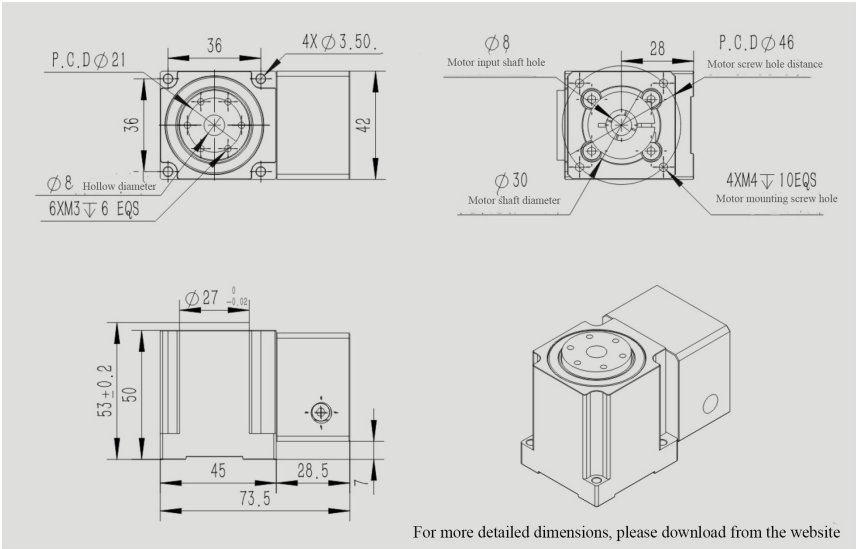
KTC40



How to order :

Series	Dimension	Reduction ratio	Motor type
KTC	40	5K	Various brands servo motor 50-100W/Step motor size 42

Specification	
Motor specification	Various brands servo motor 50 -100W/Step motor size 42
Bearing structure	Crossed Roller Bearing
Allowable torque	12N.m
Allowable speed	200rpm
Reduction ratio	1:5
Allowable axial load	100N
Posiitoning accuracy	≤1arcmin
Repeat positioning accuracy	≤10arcsec
Rotating platform parallelism	≤0.01mm
Rotating platform concentricity	≤0.01mm
Protection level	IP63
Accuracy life	20000H
Mass	0.5KG



KTC series hollow rotating platform—equipped with servo or planetary reducer



KTC series hollow rotating platform—equipped with servo or planetary reducer

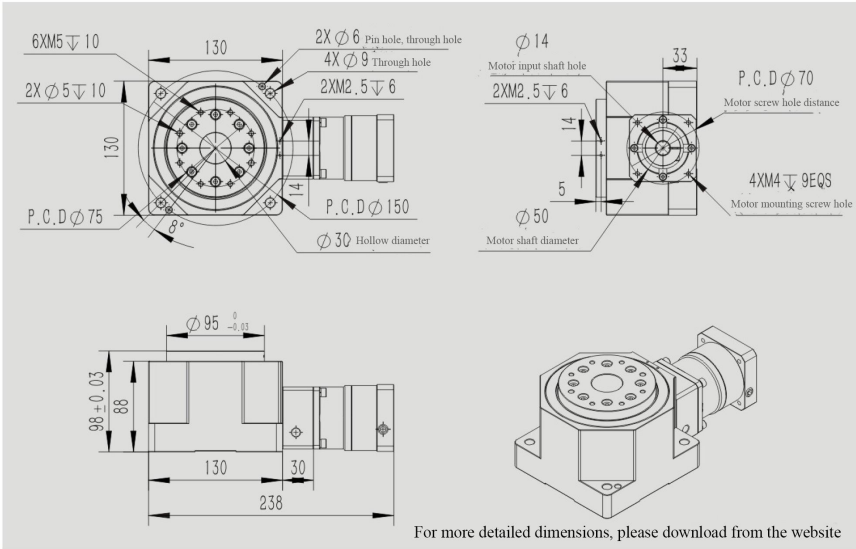


KTC60



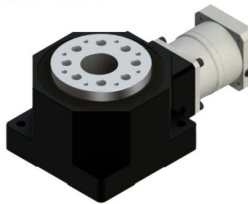
How to order :			
Series	Dimension	Reduction ratio	Motor type
KTC	60	1:9/12/15/21/30	Various brands servo motor 200-400W

Specification	
Motor specification	Various brands servo motor 200-400W
Bearing structure	Crossed Roller Bearing
Allowable torque	30N.m
Allowable speed	200rpm
Reduction ratio	1:9/12/15/21/30
Allowable axial load	5300N
Posiitoning accuracy	≤1arcmin
Repeat positioning accuracy	≤30arcsec
Rotating platform parallelism	≤0.01mm
Rotating platform concentricity	≤0.01mm
Protection level	IP63
Accuracy life	30000H
Mass	6.5KG



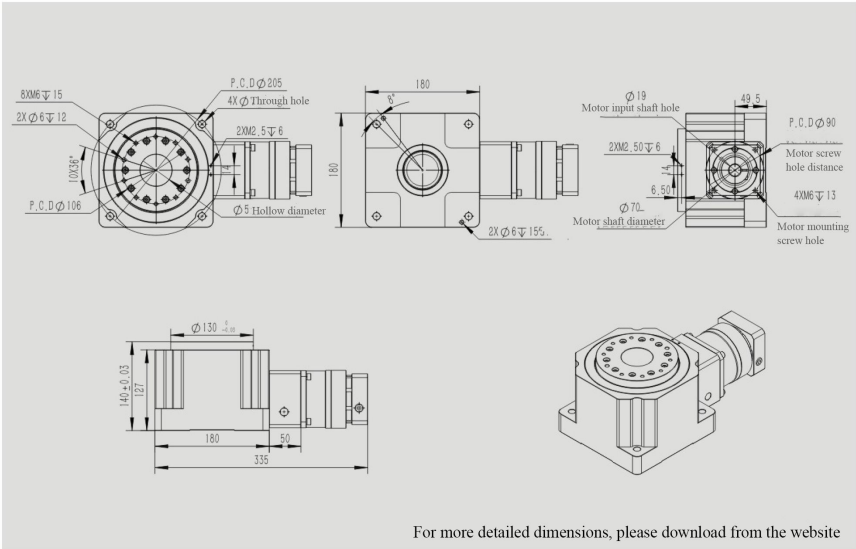
For more detailed dimensions, please download from the website

KTC90



How to order :			
Series	Dimension	Reduction ratio	Motor type
KTC	90	1:9/12/15/21/30	Various brands servo motor 750W

Specification	
Motor specification	Various brands servo motor 750W
Bearing structure	Crossed Roller Bearing
Allowable torque	60N.m
Allowable speed	200rpm
Reduction ratio	1:9/12/15/21/30
Allowable axial load	8500N
Posiitoning accuracy	≤1arcmin
Repeat positioning accuracy	≤30arcsec
Rotating platform parallelism	≤0.01mm
Rotating platform concentricity	≤0.01mm
Protection level	IP63
Accuracy life	30000H
Mass	16KG



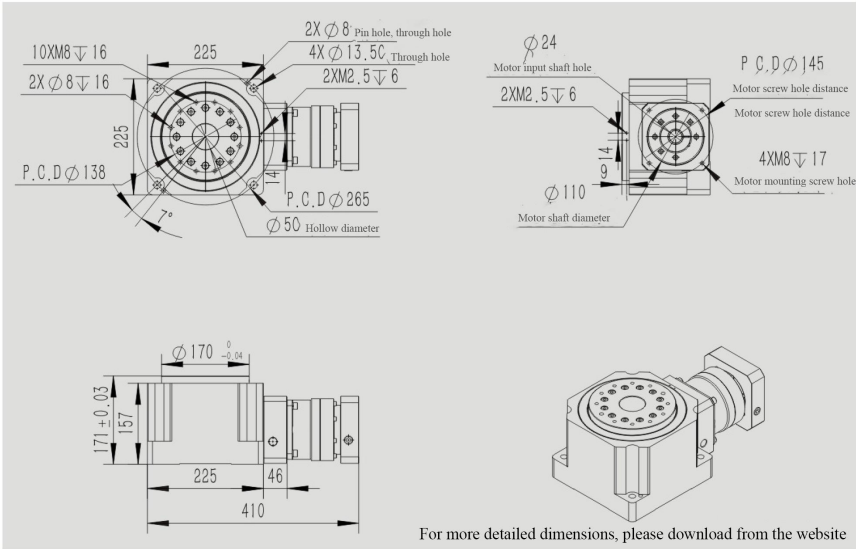
For more detailed dimensions, please download from the website



How to order :

Series	Dimension	Reduction ratio	Motor type
KTC	120	1:9/12/15/21/30	Various brands servo motor 1000-2500W

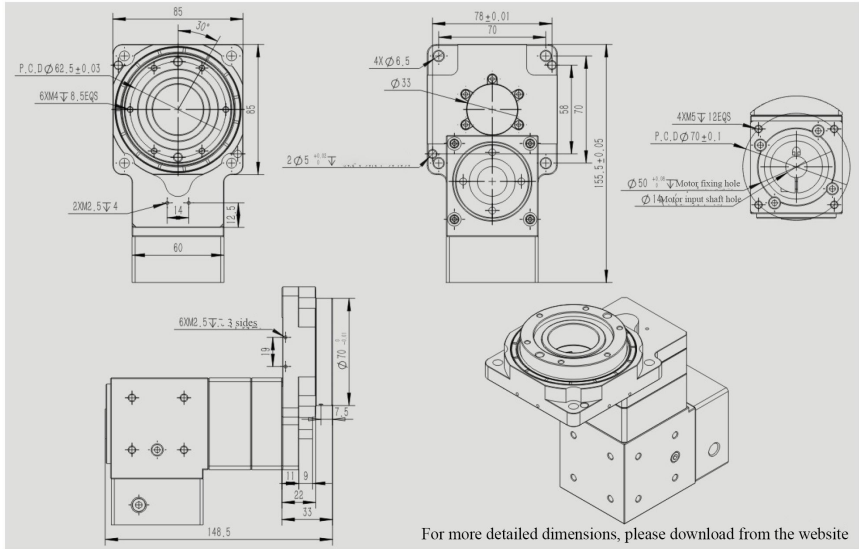
Specification	
Motor specification	Various brands servo motor 1000-2500W
Bearing structure	Crossed Roller Bearing
Allowable torque	220N.m
Allowable speed	200rpm
Reduction ratio	1:9/12/15/21/30
Allowable axial load	18000N
Posiitoning accuracy	≤1arcmin
Repeat positioning accuracy	≤30arcsec
Rotating platform parallelism	≤0.01mm
Rotating platform concentricity	≤0.01mm
Protection level	IP63
Accuracy life	30000H
Mass	36KG



How to order :

Series	Dimension	Reduction ratio	Motor type
KTY	85	20K/30K/50K	Various brands servo motor 200-400W

Specification	
Motor specification	Various brands servo motor 200-400W
Bearing structure	Crossed Roller Bearing
Allowable torque	8N.m
Allowable speed	150rpm
Reduction ratio	1:20/30/50
Allowable axial load	500N
Posiitoning accuracy	±30arcsec
Repeat positioning accuracy	±15arcsec
Rotating platform parallelism	±0.003mm
Rotating platform concentricity	±0.003mm
Protection level	IP63
Accuracy life	20000H
Mass	3KG



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Series	Dimension	Reduction ratio	Motor type
KTY	130	20K/30K/50K	Various brands servo motor 200-4000W

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Series	Dimension	Reduction ratio	Motor type
KTY	200	20K/30K/50K	Various brands servo motor 750W

Technical drawing of the 200mm motor frame showing front, side, and top views with dimensions and callouts.

Front View Dimensions:

- Overall width: 180
- Inner width: 170
- Top flange thickness: 30
- Top flange outer diameter: $2 \times \varnothing 6^{+0.03}$
- Top flange inner diameter: $\varnothing 100$
- Top flange hole diameter: $4 \times \varnothing 11$
- Top flange hole pitch circle diameter: $P.C.D \varnothing 155 \pm 0.03$
- Top flange hole quantity: $6 \times M6 \nabla 10EQS$
- Top flange hole quantity: $2 \times M2.5 \nabla 4.5$
- Top flange hole quantity: $4 \times M5 \nabla 12EQS$
- Top flange hole quantity: $P.C.D \varnothing 90 \pm 0.1$
- Top flange hole quantity: $\varnothing 70^{+0.03} \nabla$ Motor fixing hole
- Top flange hole quantity: $\varnothing 1$ Motor fixing screw hole
- Top flange hole quantity: $2 \times M2.5 \nabla 3$ sides
- Top flange hole quantity: 22
- Top flange hole quantity: 19
- Top flange hole quantity: 15.5
- Top flange hole quantity: 8.5
- Top flange hole quantity: 37.5
- Top flange hole quantity: 80 ± 0.05
- Top flange hole quantity: 224.5 ± 0.2
- Top flange hole quantity: $\varnothing 170^{+0.03}$

Side View Dimensions:

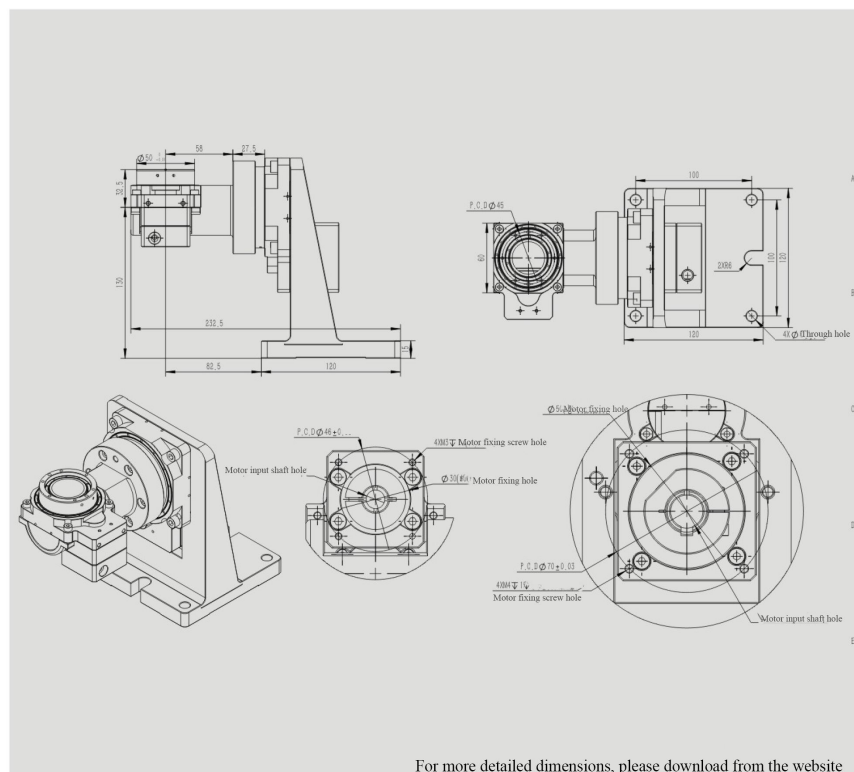
- Overall height: 200
- Inner height: 200
- Inner diameter: $\varnothing 100$
- Inner hole diameter: $4 \times \varnothing 11$
- Inner hole pitch circle diameter: $P.C.D \varnothing 155 \pm 0.03$
- Inner hole quantity: $6 \times M6 \nabla 10EQS$
- Inner hole quantity: $2 \times M2.5 \nabla 4.5$
- Inner hole quantity: $4 \times M5 \nabla 12EQS$
- Inner hole quantity: $P.C.D \varnothing 90 \pm 0.1$
- Inner hole quantity: $\varnothing 70^{+0.03} \nabla$ Motor fixing hole
- Inner hole quantity: $\varnothing 1$ Motor fixing screw hole
- Inner hole quantity: $2 \times M2.5 \nabla 3$ sides
- Inner hole quantity: 22
- Inner hole quantity: 19
- Inner hole quantity: 15.5
- Inner hole quantity: 8.5
- Inner hole quantity: 37.5
- Inner hole quantity: 80 ± 0.05
- Inner hole quantity: 224.5 ± 0.2
- Inner hole quantity: $\varnothing 170^{+0.03}$

Top View Dimensions:

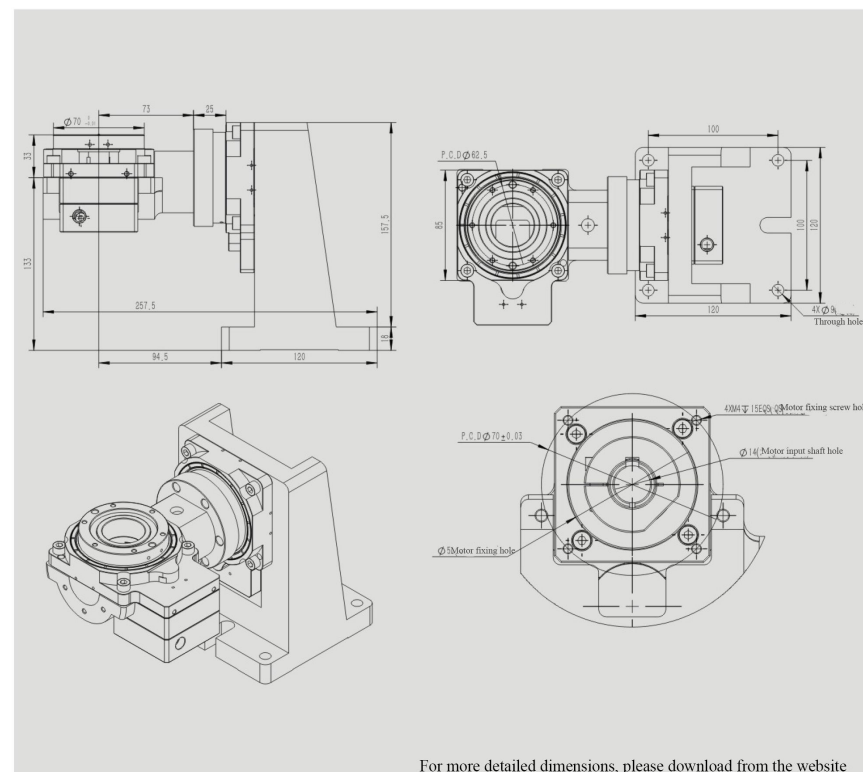
- Overall width: 180
- Inner width: 170
- Top flange thickness: 30
- Top flange outer diameter: $2 \times \varnothing 6^{+0.03}$
- Top flange inner diameter: $\varnothing 100$
- Top flange hole diameter: $4 \times \varnothing 11$
- Top flange hole pitch circle diameter: $P.C.D \varnothing 155 \pm 0.03$
- Top flange hole quantity: $6 \times M6 \nabla 10EQS$
- Top flange hole quantity: $2 \times M2.5 \nabla 4.5$
- Top flange hole quantity: $4 \times M5 \nabla 12EQS$
- Top flange hole quantity: $P.C.D \varnothing 90 \pm 0.1$
- Top flange hole quantity: $\varnothing 70^{+0.03} \nabla$ Motor fixing hole
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- Top flange hole quantity: 15.5
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- Top flange hole quantity: 37.5
- Top flange hole quantity: 80 ± 0.05
- Top flange hole quantity: 224.5 ± 0.2
- Top flange hole quantity: $\varnothing 170^{+0.03}$

For more detailed dimensions, please download from the website

www.kamidrive.com 26

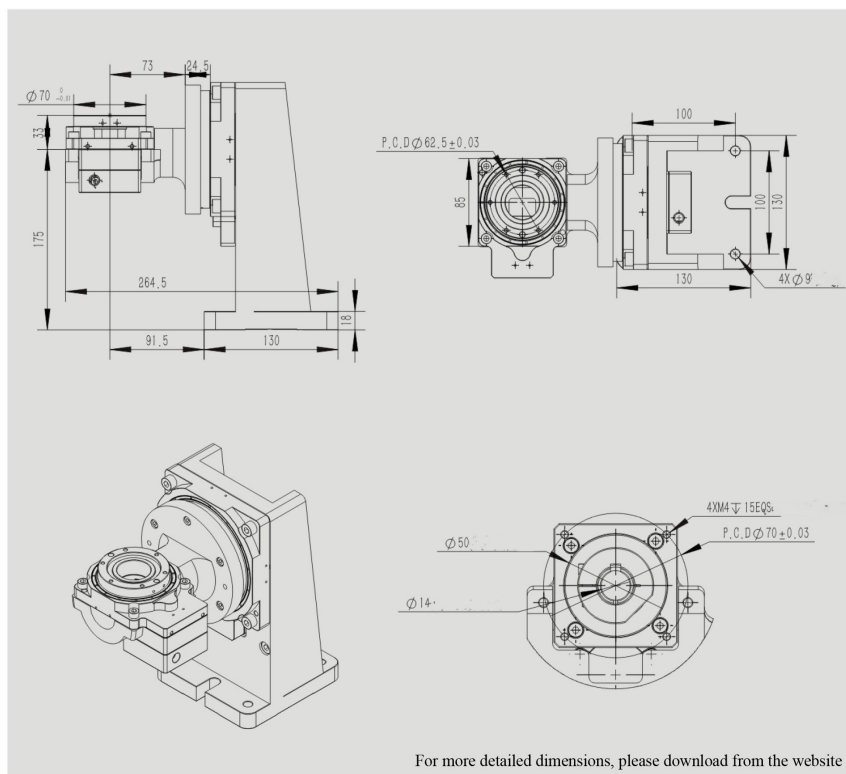
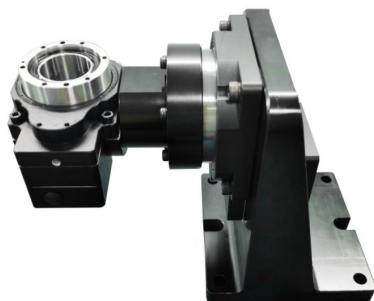


For more detailed dimensions, please download from the website



For more detailed dimensions, please download from the website

4 or 5 axis 85 - 10 K/ 130 -188 K

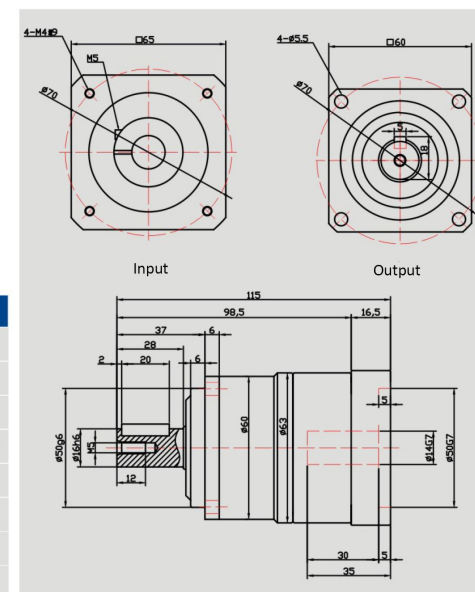


For more detailed dimensions, please download from the website

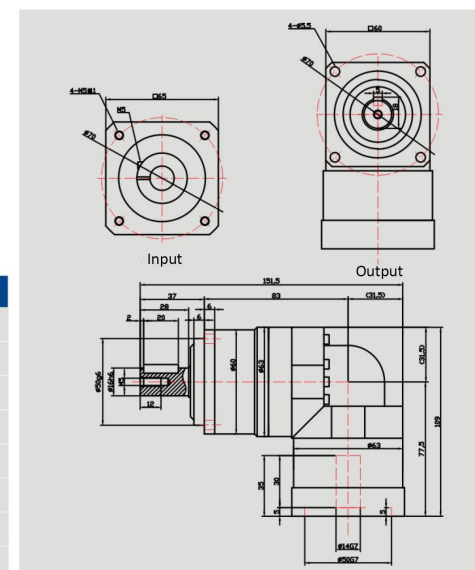
KB060



Specification					
Reduction ratio	3	4	5	7	10
Rated output torque (Nm)	19	28	28	28	19
Maximum output torque (Nm)	37	52	52	52	37
Radial force (N)	430	470	510	570	640
Axial force (N)	310	360	390	460	530
Rated input speed (rpm)	3000				
Maximum input speed (rpm)	6000				
Tightening screw torque (Nm)	10				

**KBR060**

Specification					
Reduction ratio	3	4	5	7	10
Rated output torque (Nm)	13	17	23	25	17
Maximum output torque (Nm)	26	34	46	46	33
Radial force (N)	430	470	510	570	640
Axial force (N)	310	360	390	460	530
Rated input speed (rpm)	3000				
Maximum input speed (rpm)	6000				
Tightening screw torque (Nm)	10				

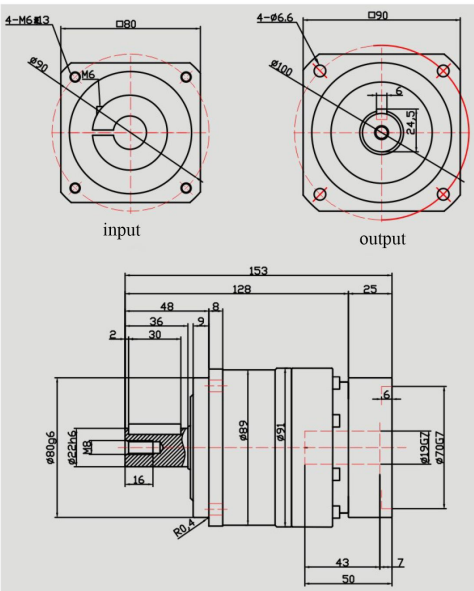


KB090



Specification

Reduction ratio	3	4	5	7	8	10
Rated output torque (Nm)	52	78	78	78	78	52
Maximum output torque (Nm)	84	130	130	130	130	84
Radial force (N)	810	890	960	1100	1100	1200
Axial force (N)	930	1100	1200	1300	1400	1600
Rated input speed (rpm)	3000					
Maximum input speed (rpm)	6000					
Tightening screw torque (Nm)	10					

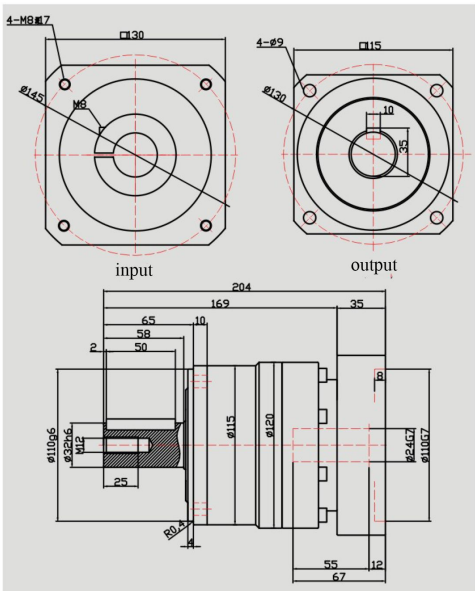


KB115



Specification

Reduction ratio	3	4	5	7	10
Rated output torque (Nm)	126	126	189	189	126
Maximum output torque (Nm)	236	346	346	346	236
Radial force (N)	1300	1500	1600	1800	2000
Axial force (N)	1500	1700	1900	2100	2500
Rated input speed (rpm)	3000				
Maximum input speed (rpm)	6000				
Tightening screw torque (Nm)	40				

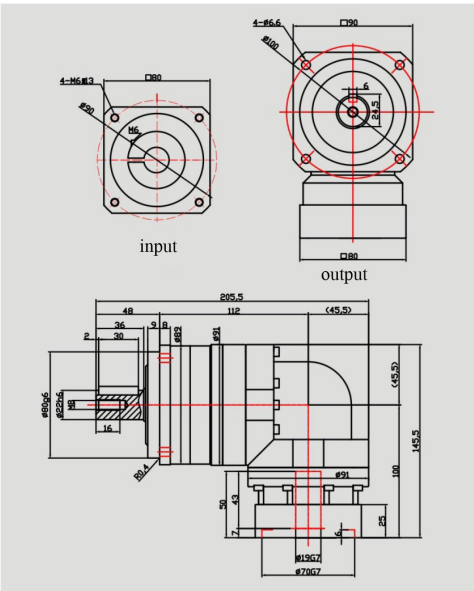


KBR090



Specification

Reduction ratio	3	4	5	7	8	10
Rated output torque (Nm)	46	62	66	66	66	46
Maximum output torque (Nm)	68	92	92	92	92	68
Radial force (N)	810	890	960	1100	1100	1200
Axial force (N)	930	1100	1200	1300	1400	1600
Rated input speed (rpm)	3000					
Maximum input speed (rpm)	6000					
Tightening screw torque (Nm)	20					

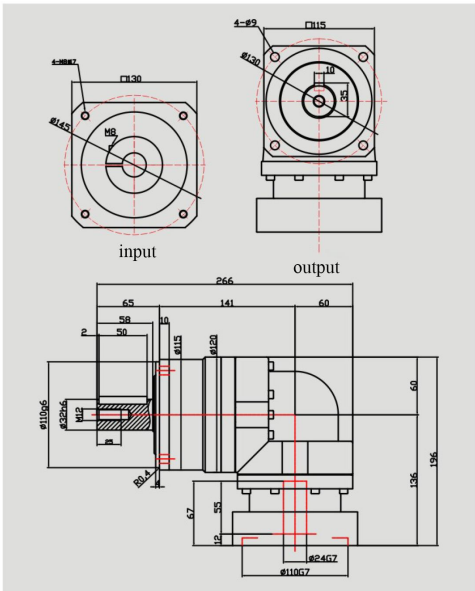


KBR115



Specification

Reduction ratio	3	4	5	7	10
Rated output torque (Nm)	80	110	130	160	120
Maximum output torque (Nm)	160	210	250	310	210
Radial force (N)	1300	1500	1600	1800	2000
Axial force (N)	1500	1700	1900	2100	2500
Rated input speed (rpm)	3000				
Maximum input speed (rpm)	6000				
Tightening screw torque (Nm)	40				



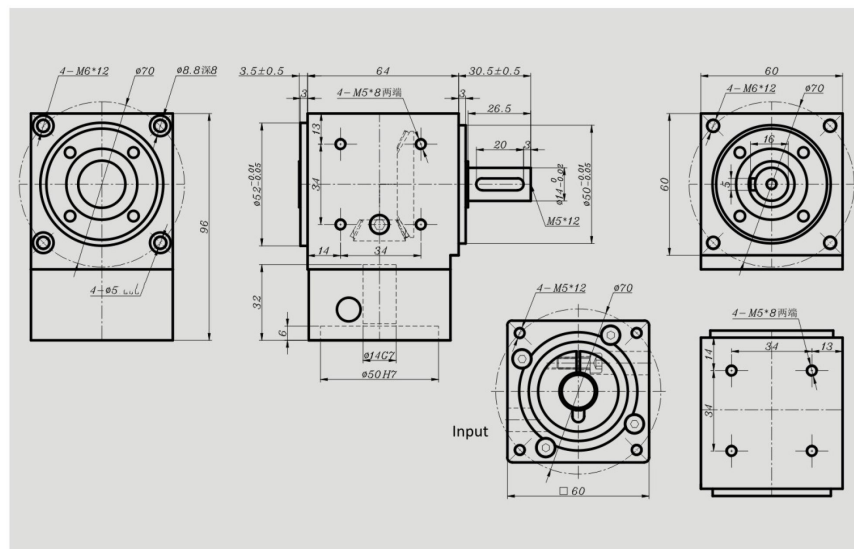
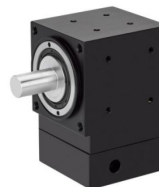
KBY060

How to order :

Series	Dimension	Reduction ratio	Motor type
KBY	60	1:2K/3K/5K	Servo motor 200/400W

Specification

Specification			
Reduction ratio	2	3	5
Rated output torque (Nm)	35	30	25
Maximum output torque (Nm)	52	45	38
Radial force (N)	560		
Axial force (N)	230		
Rated input speed (rpm)	2000		
Maximum input speed (rpm)	3000		
Tightening screw torque (Nm)	10		

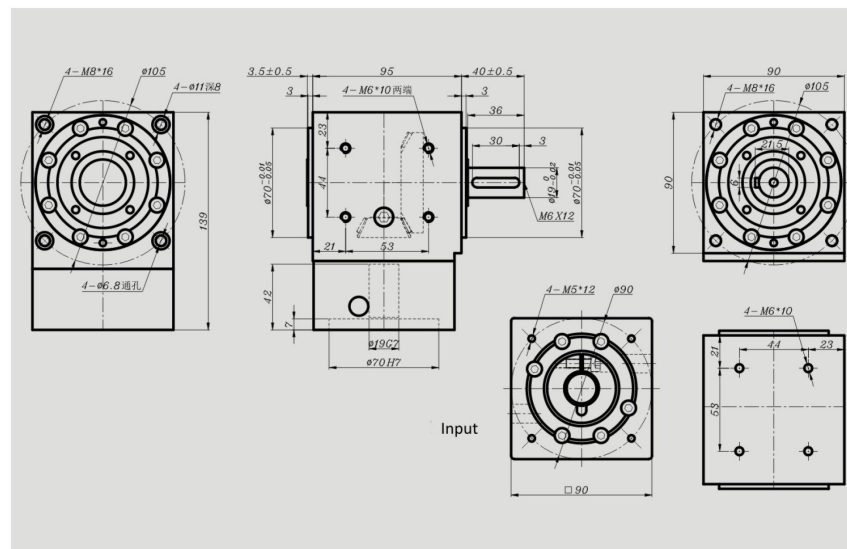
**KBY090**

How to order :

Series	Dimension	Reduction ratio	Motor type
KBY	90	1:2K/3K/5K	Servo motor 750W

Specification

Specification			
Reduction ratio	2	3	5
Rated output torque (Nm)	50	45	40
Maximum output torque (Nm)	75	68	60
Radial force (N)	1050		
Axial force (N)	550		
Rated input speed (rpm)	2000		
Maximum input speed (rpm)	3000		
Tightening screw torque (Nm)	20		



Hollow Rotating Platform Application Description

A revolutionary new product in
rotary motion mechanism

凯米传动
KAMI DRIVE

Structure of hollow rotating platform – servo system

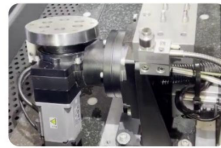
凯米传动
KAMI DRIVE

The hollow rotating platform is a new type of rotating load device, which combines high transmission efficiency, high precision, high rigidity and high cost performance, and combines the advantages of servo motors, cam dividers and direct drive motors.

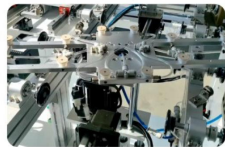
The use of high-precision gears and cross roller bearings improves torque, rigidity and the load is more stable. It can be divided at any angle with a servo motor or a stepper motor, which can meet the arbitrary angle control that the divider cannot achieve, and the positioning accuracy is comparable to a direct drive motor, which can achieve precise positioning of the load.



Welding machine



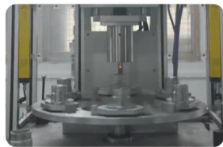
Sparking machine



Cutting machine



Vision screening machine



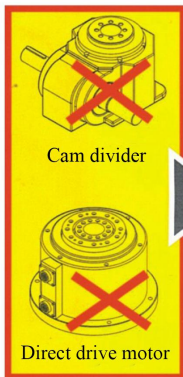
Servo pressing machine



Hollow rotating platform

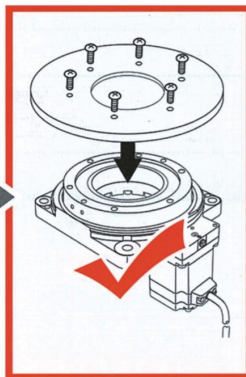


Paper cup forming machine



Cam divider

Direct drive motor



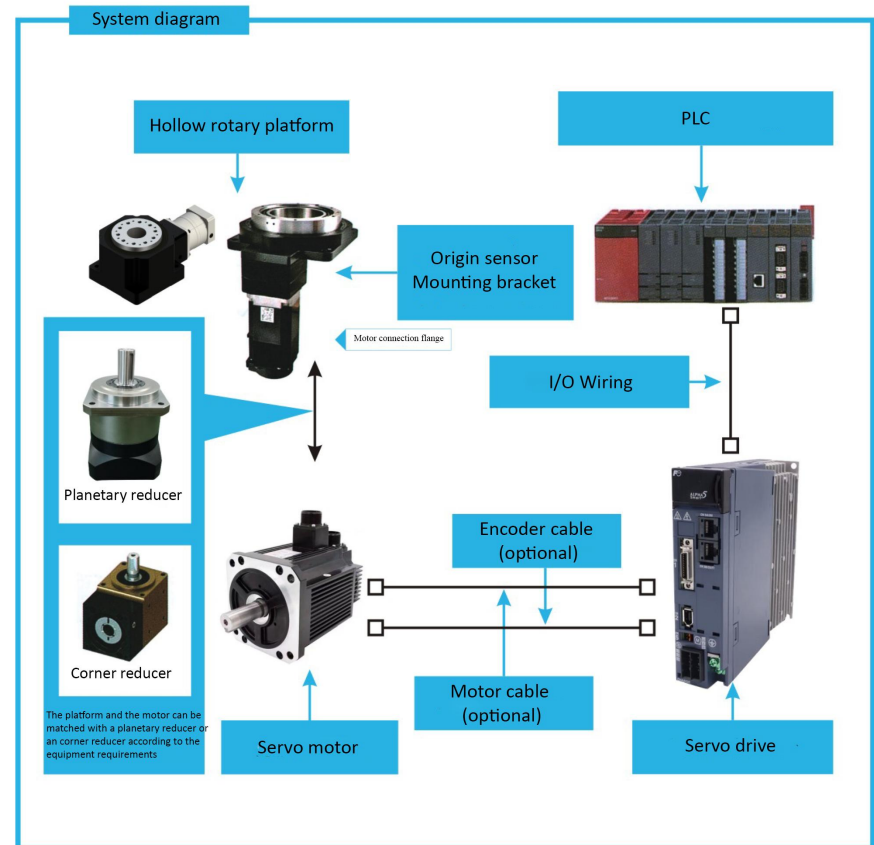
■ The durability of the device can be improved through the direct connection between the robot arm and the hollow rotating platform, thereby saving time and cost in the design and operation process compared to the use of mechanical tools such as conventional pulleys.

■ Motor configuration:
Suitable for various brands of stepper and servo motors

■ High precision positioning.
Positioning accuracy ≤ 15 arcsec, repeat positioning accuracy at ± 5 arcsec

■ Large diameter hollow structure
Make the installation more convenient, particularly in complex wiring and piping environments.

Standard configuration	Platform body x 1	Optional accessories	Step, servo motor 
			Origin sensor 



Motor type	Types of motors that the KAMI rotating device can be connected to
Rotating platform bearing	The type of bearing used in the rotating platform
Allowable torque	The mechanical strength critical value of the reduction mechanism, including acceleration torque and load inertia, must be used within this allowable torque range.
Allowable speed	The permissible value of rotation speed base on the mechanical conditions of rotating platform
Moment of inertia	The sum of the values of the motor rotor inertia and the reduction mechanism inertia converted on the rotating platform
Moment of inertia	The allowable value of the axial load acting on the axis of the rotary platform
Allowable inertial moment load	The allowable value of the moment of inertia load is calculated by multiplying the eccentricity of the center by the load when a load is applied at a position offset from the center of the rotating platform so that a force that causes the rotating platform to tilt acts
Positioning accuracy	The difference value between the theoretical rotation angle and the actual rotation angle of the rotary platform when locating any point within 360 degrees.
Repeat positioning accuracy	Indicates the difference value generated when positioning the same position repeatedly from the same direction
Rotating platform parallelism	The parallelism of the rotating platform relative to the base mounting surface during operation
Rotating platform concentricity	The concentricity difference value of the inner diameter and outer diameter of the rotating platform when there is no load
Allowable input speed	The allowable input speed is determined by the mechanical strength of the reducer structure
Backlash	It refers to the gear clearance of the rotating platform after the motor shaft is fixed
Breaking torque	When the product is subjected to this torque, the structure will be destroyed
Accuracy life	The product can maintain the exact life as designed in the normal use environment
Protection level	The machine protection structure based on IEC529, EN60034-5(=IEC60034-5) is dustproof and waterproof

Note 1: The units of torque are interchangeable

Torque unit	1 N.m	1 N.cm	1 kgf.m	1 kgf.cm	1 lbf.ft	1 lbf.in
1 N.m	1	10 ²	0.10197	10.197	0.7376	8.8509
1 N.cm	10 ⁻²	1	1.0197×10 ⁻³	0.10197	7.376×10 ⁻³	8.8509×10 ⁻²
1 kgf.m	9.8066	980.665	1	10 ²	7.233	86.79
1 kgf.cm	9.8066×10 ⁻²	9.8066	10 ⁻²	1	7.233×10 ⁻²	0.8680
1 lbf.ft	1.356	1.356×10 ²	0.1383	13.83	1	12
1 lbf.in	0.113	11.3	1.152×10 ⁻²	1.152	8.333×10 ⁻²	1

Note 2: How to express angle units

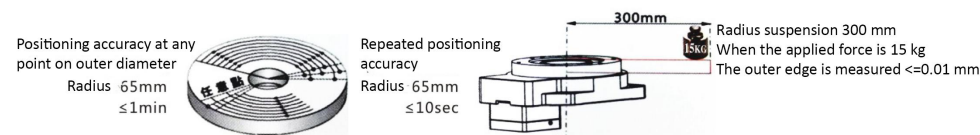
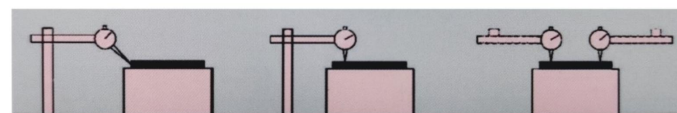
Angle Unit	Value	Symbol	Abbreviation
Degree	1/360 circle	°	Deg
Arcminute	1/60 degree	'	arcmin, amin, MOA
Arcsecond	1/60 arcminute	"	arcsec
One thousandth of an arcsecond	1/1000 arcsecond		mas

Note 03: IP protection level

IP Code	Dust protection (first digit)	IP Code	Water resistance (Second digit)
IP 0 X	No dust protection	IPX 0	No special protection function
IP 1 X	Can block objects with a diameter of more than 50mm	IPX 1	Vertically falling water will not damage the product
IP 2 X	Can block objects with a length of more than 80mm, a diameter of more than 12mm	IPX 2	When tilted at 15 degrees, it can still prevent water drops from entering
IP 3 X	Can block objects with a diameter and thickness of more than 2.5mm	IPX 3	No damage from water spray within 60 degrees from vertical direction
IP 4 X	Can block objects with a thickness and diameter exceeding 1.0mm	IPX 4	No damage from water splashing from any direction
IP 5 X	Prevents dust from entering and affecting the device	IPX 5	No damage from water sprayed directly onto the device
IP 6 X	Prevents all dust from entering	IPX 6	No water can enter the device
		IPX 7	The device is not damaged when immersed in water under certain
		IPX 8	Can be used underwater

Positioning accuracy detection

Disk concentricity detection $\pm 0.002\text{mm}$ Disc rotation amplitude $\pm 0.002\text{mm}$ Parallelism between plate and base $\pm 0.0015\text{mm}$



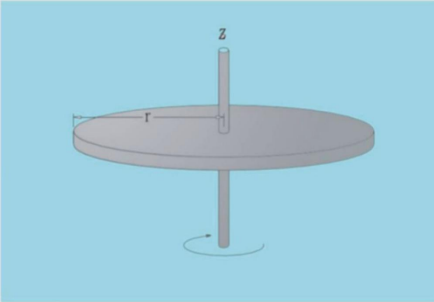
Selection example

Select platform series :
Select load type :
Select installation method :

Weight kg
Radius mm

Workstation angle : °
Operation time : s
Acceleration time : s
Required accuracy : mm

Calculate



*For more technical information and 2D, 3D drawings please contact us

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